

6.2 Linear and Almost Linear Sys (continued)

L

last time: $x' = F(x, y)$
 $y' = G(x, y)$

is almost/locally linear if near critical pt (x_0, y_0)

it behaves like

$$\vec{x}' = A\vec{x} + \vec{g}(\vec{x}) \quad \text{such that} \quad \lim_{(x,y) \rightarrow (x_0, y_0)} \frac{|\vec{g}|}{|\vec{x}|} = 0$$

generally, there is a different A near each critical pt

example from last time:

$$x' = -x + xy$$

$$y' = -2y + 8xy \quad \text{has a critical pt at } \left(\frac{1}{4}, 1\right)$$

$$\text{define } u = x - \frac{1}{4} \quad v = y - 1 \quad x = u + \frac{1}{4} \quad y = v + 1$$

$$u' = x' \quad v' = y'$$

rewrite system

$$u' = -\left(u + \frac{1}{4}\right) + \left(u + \frac{1}{4}\right)(v + 1) = \frac{1}{4}v + uv$$

$$v' = \dots = 8u + 8uv$$

$$\begin{bmatrix} u' \\ v' \end{bmatrix} = \underbrace{\begin{bmatrix} 0 & \frac{1}{4} \\ 8 & 0 \end{bmatrix}}_{A \text{ near } \left(\frac{1}{4}, 1\right)} \begin{bmatrix} u \\ v \end{bmatrix} + \begin{bmatrix} uv \\ 8uv \end{bmatrix}$$

A near $\left(\frac{1}{4}, 1\right)$

there is a different (more efficient) way to find the A matrix

→ linearize the nonlinear system

$$x' = F(x, y)$$

$$y' = G(x, y)$$

do Taylor series expansion for F and G near critical pt (x_0, y_0)

$$F(x, y) = F(x_0, y_0) + \frac{\partial F}{\partial x}(x_0, y_0) \underbrace{(x-x_0)}_u + \frac{\partial F}{\partial y}(x_0, y_0) \underbrace{(y-y_0)}_v + \dots$$

higher order
(not important)

$$G(x, y) = G(x_0, y_0) + \frac{\partial G}{\partial x}(x_0, y_0) \underbrace{(x-x_0)}_u + \frac{\partial G}{\partial y}(x_0, y_0) \underbrace{(y-y_0)}_v + \dots$$

crit. pt.

near (x_0, y_0) $x' = F(x, y)$ becomes
 $y' = G(x, y)$

$$u' = \frac{\partial F}{\partial x}(x_0, y_0) u + \frac{\partial F}{\partial y}(x_0, y_0) v$$

$$v' = \frac{\partial G}{\partial x}(x_0, y_0) u + \frac{\partial G}{\partial y}(x_0, y_0) v$$

$$\begin{bmatrix} u' \\ v' \end{bmatrix} = \begin{bmatrix} F_x(x_0, y_0) & F_y(x_0, y_0) \\ G_x(x_0, y_0) & G_y(x_0, y_0) \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix}$$

Jacobian matrix \rightarrow our A matrix near (x_0, y_0)

example

$$x' = x^2 + y^2 - 6 = F$$

$$y' = x^2 - y = G$$

$$\text{cp: } (\sqrt{2}, 2), (-\sqrt{2}, 2)$$

$$\text{Jacobian matrix: } J(x, y) = \begin{bmatrix} 2x & 2y \\ 2x & -1 \end{bmatrix}$$

linearized near $(\sqrt{2}, 2)$

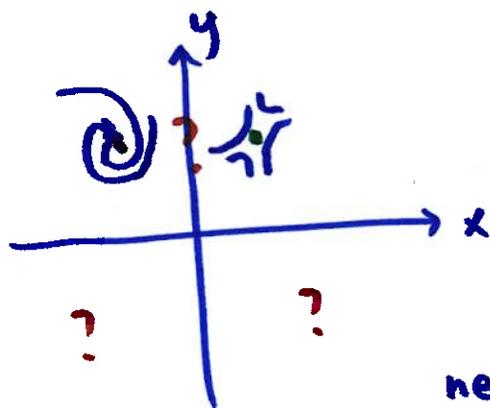
$$J = \begin{bmatrix} 2\sqrt{2} & 4 \\ 2\sqrt{2} & -1 \end{bmatrix}$$

$$\text{system acts like } \vec{x}' = \begin{bmatrix} 2\sqrt{2} & 4 \\ 2\sqrt{2} & -1 \end{bmatrix} \vec{x}$$

$$\lambda \approx 4.8, -3$$

Saddle point
unstable

(not sensitive to
perturbation)



near $(-\sqrt{2}, 2)$

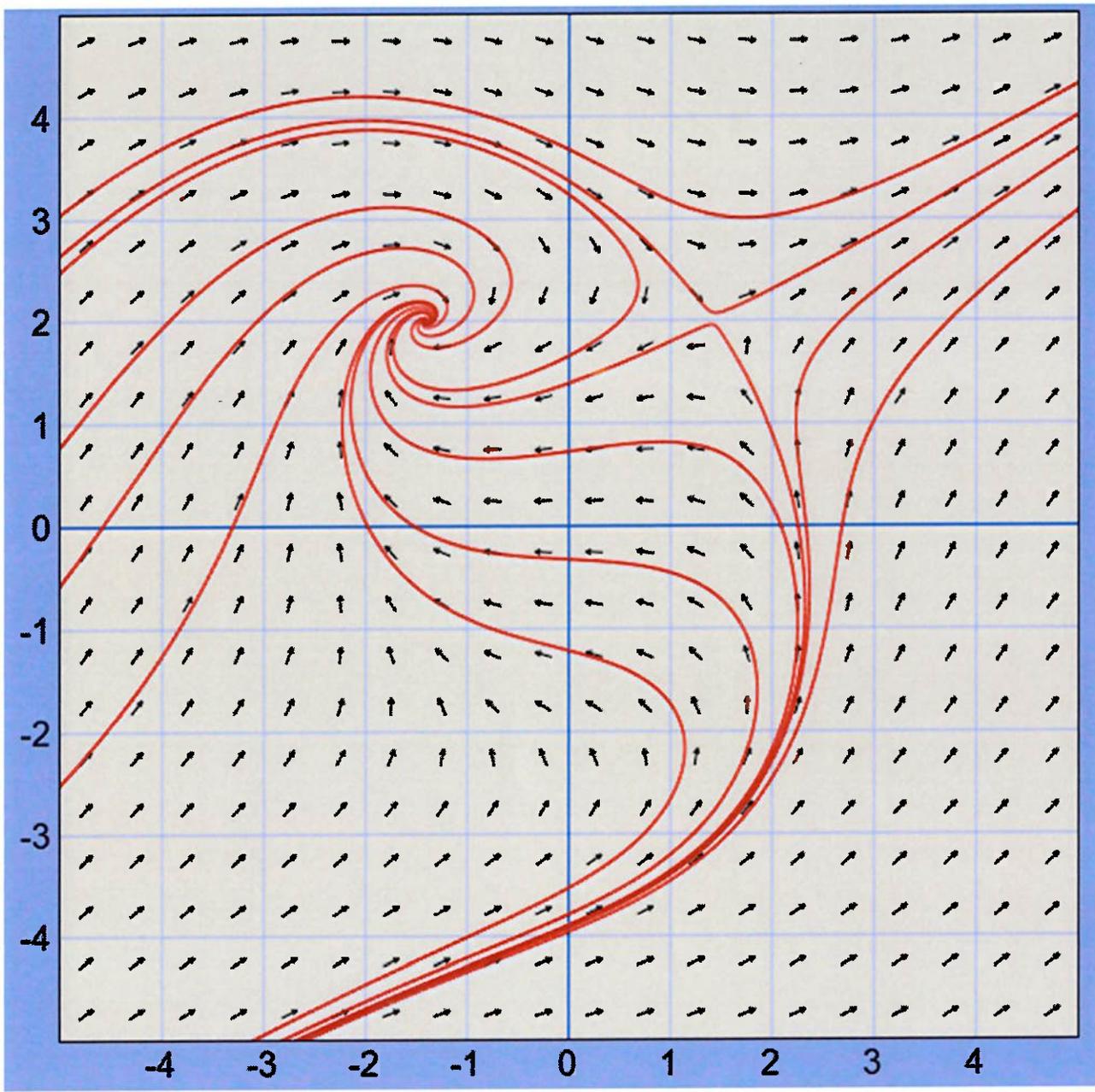
$$J = \begin{bmatrix} -2\sqrt{2} & 4 \\ -2\sqrt{2} & -1 \end{bmatrix}$$

$$\lambda \approx -2 \pm 3.2i$$

spiral sink

asympt. stable

(not sensitive to
perturbation)



example

$$x' = 2xy = F$$

$$y' = 1 - x^2 + y^2 = G$$

$$cp: (1, 0), (-1, 0)$$

$$J = \begin{bmatrix} F_x & F_y \\ G_x & G_y \end{bmatrix} = \begin{bmatrix} 2y & 2x \\ -2x & 2y \end{bmatrix}$$

$$J(1, 0) = \begin{bmatrix} 0 & 2 \\ -2 & 0 \end{bmatrix}$$

$$\lambda = \pm 2i$$

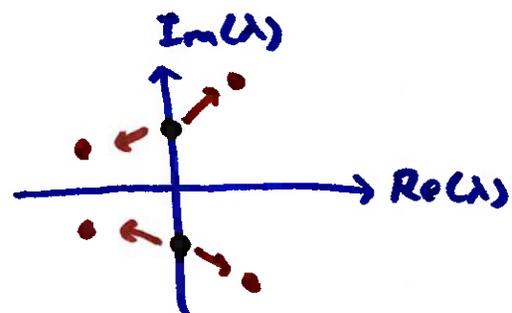
linearized sys. says center
(stable) **Sensitive to perturbation**
true behavior could still be
a center but we can't tell
from linearization

$$J(-1, 0) = \begin{bmatrix} 0 & -2 \\ 2 & 0 \end{bmatrix}$$

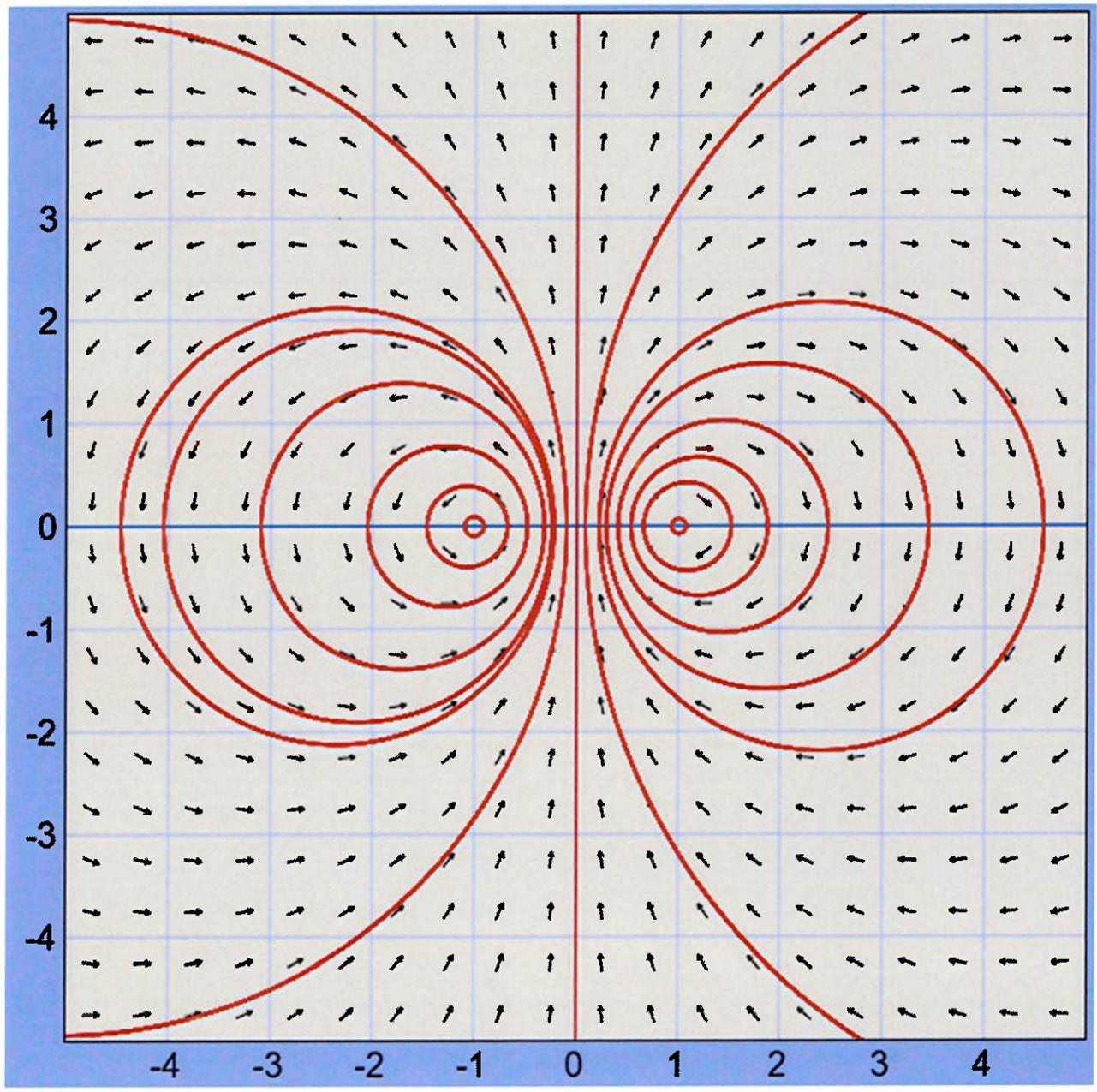
$$\lambda = \pm 2i$$

same story as the
other cp.

we can't be sure what the true picture is like
w/o either plotting the nonlinear phase diagram
or solving the system (for this sys, the sub $u = y^2/x$
can solve the system)



in this case,
the linearized
sys tell us
the "truth"



Example

$$x' = -3y + ay(x^2 + y^2)$$

$$y' = 3x + ay(x^2 + y^2) \quad a \text{ is some constant}$$

$$cp: (0, 0)$$

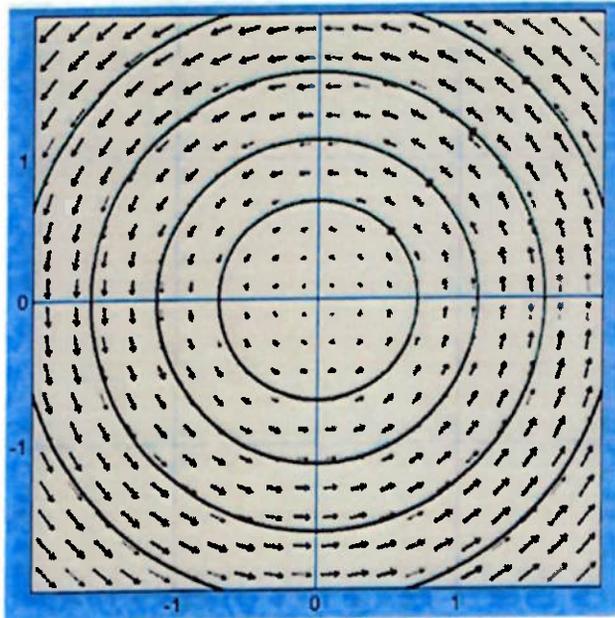
$$J = \begin{bmatrix} 2xya & -3 + ax^2 + 3y^2a \\ 3 + 2axy & 3ay^2 + ax^2 \end{bmatrix}$$

$$J(0, 0) = \begin{bmatrix} 0 & -3 \\ 3 & 0 \end{bmatrix}$$

no a here.

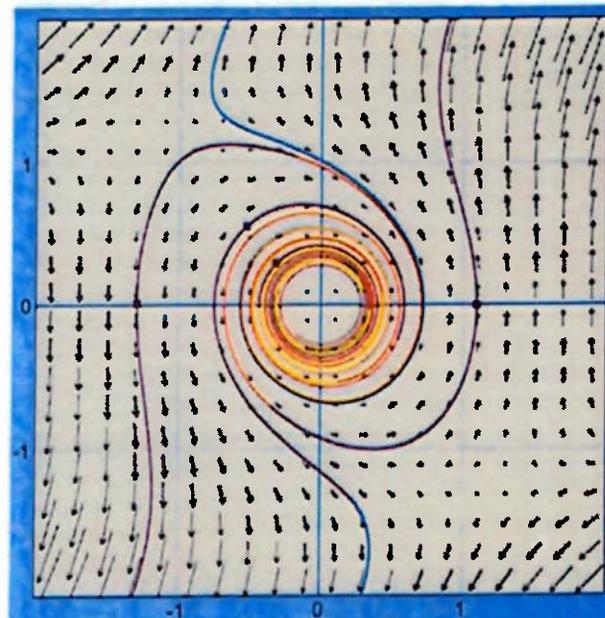
clearly " a " is doing something

but linearization completely lost it



**Linearized
(stable center)**

**Nonlinear $a=1$
(unstable
spiral point)**



**Nonlinear $a=-1$
(asymptotically
stable spiral
point)**

